

# MATB24 Final Review

## ① Vector Space

- def: ① closed under addition  $\forall v, w \in V, v + w \in V$   
② closed under scalar multiplication  $\forall v \in V, r \in \mathbb{R}, rv \in V$   
③  $A_1 - A_2$   $S_1 - S_2$

•  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is a basis of  $V$  if every  $v \in V$  can be expressed uniquely as a linear combination of  $\{\vec{v}_1, \dots, \vec{v}_n\}$

## ② Subspace

- def: ① non-empty  
② closed under addition  $\forall v, w \in V, v + w \in V$   
③ closed under scalar multiplication  $\forall v \in V, r \in \mathbb{R}, rv \in V$

• if  $V$  has a dimension  $n$ ,  $x \in V$  be L.I and  $|x| = n$ ,  $\text{span}(x) = V$ ,  $|y| = n$ . then  $x \leq y \leq y$

•  $\text{span}(v_1, \dots, v_n) = \text{span}(w_1, \dots, w_m) \iff v_1, \dots, v_n \in \text{span}(w_1, \dots, w_m)$  and  $w_1, \dots, w_m \in \text{span}(v_1, \dots, v_n)$

## ③ Linear Transformation

- Def: ①  $T(\vec{v}_1 + \vec{v}_2) = T(\vec{v}_1) + T(\vec{v}_2)$   
②  $T(r\vec{v}) = rT(\vec{v})$

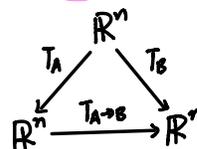
injective:  $T(v) = T(w) \iff v = w$  /  $\text{ker}(T) = 0$

surjective:  $\forall w \in W, \exists v \in V$  st  $T(v) = w$  /  $\text{Im}(T) = W$

## ④ Change of Basis

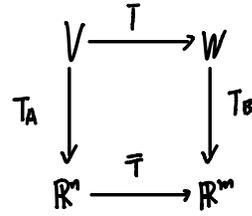
$$T_A: [v]_E \mapsto [v]_A \quad T_B: [v]_E \mapsto [v]_B$$

$$T_{A \rightarrow B}: [v]_A \mapsto [v]_B, C_{A \rightarrow B} [v]_A = [v]_B, \text{ where } C_{A \rightarrow B} = \begin{bmatrix} [a_1]_B & [a_2]_B & \dots & [a_n]_B \\ | & | & & | \end{bmatrix}$$



$$\bar{T}: [V]_A \rightarrow [T(v)]_B$$

$$[T]_{A,B} [v]_A = [T(v)]_B, \text{ where } [T]_{A,B} = \begin{bmatrix} | & & | \\ [T(a_1)]_B & & [T(a_n)]_B \\ | & & | \end{bmatrix}$$



$$[T]_{A,A} [v]_A = [T(v)]_A, \text{ where } [T]_{A,A} = \begin{bmatrix} | & & | \\ [T(a_1)]_A & & [T(a_n)]_A \\ | & & | \end{bmatrix}$$

## ⑤ Inner Product Space

- Def: ①  $\langle \vec{v}, \vec{w} \rangle = \langle \vec{w}, \vec{v} \rangle \quad \forall \vec{v}, \vec{w} \in V$   
 ②  $\langle \vec{u} + \lambda \vec{v}, \vec{w} \rangle = \langle \vec{u}, \vec{w} \rangle + \lambda \langle \vec{v}, \vec{w} \rangle$   
 ③  $\langle \vec{v}, \vec{v} \rangle \geq 0 \quad \forall \vec{v} \in V$  and  $\langle \vec{v}, \vec{v} \rangle = 0 \Leftrightarrow \vec{v} = \vec{0}_V$

- $|\langle \vec{u}, \vec{v} \rangle| \leq \|\vec{u}\| \|\vec{v}\|$
- $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$
- $\theta = \arccos \left( \frac{\langle \vec{v}, \vec{w} \rangle}{\|\vec{v}\| \|\vec{w}\|} \right)$

$$\begin{aligned} \vec{v} &= \vec{v}_{\vec{w}} + \vec{v}_{\vec{w}^\perp} \\ &= \text{Proj}_{\vec{w}} \vec{v} + \vec{v} - \text{Proj}_{\vec{w}} \vec{v} \\ &= \left( \frac{\langle \vec{v}, \vec{w} \rangle}{\|\vec{w}\|^2} \vec{w} \right) + \left( \vec{v} - \frac{\langle \vec{v}, \vec{w} \rangle}{\|\vec{w}\|^2} \vec{w} \right) \end{aligned}$$

### Gram Schmidt process

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is a basis of  $V$ , find  $\{\vec{u}_1, \dots, \vec{u}_n\}$  which is an orthonormal basis

$$\vec{u}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|}$$

$$\vec{y}_2 = \vec{v}_2 - (\vec{v}_2 \cdot \vec{u}_1) \vec{u}_1, \quad \vec{u}_2 = \frac{\vec{y}_2}{\|\vec{y}_2\|}$$

$$\vec{y}_3 = \vec{v}_3 - (\vec{v}_3 \cdot \vec{u}_1) \vec{u}_1 - (\vec{v}_3 \cdot \vec{u}_2) \vec{u}_2, \quad \vec{u}_3 = \frac{\vec{y}_3}{\|\vec{y}_3\|}$$

note:  $\text{proj}_{\vec{v}} \vec{x} = (\alpha \cdot \vec{v}_1) \vec{v}_1 + (\alpha \cdot \vec{v}_2) \vec{v}_2 + \dots + (\alpha \cdot \vec{v}_n) \vec{v}_n$ , if  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is an orthonormal basis

- if  $V = \text{sp}\{\vec{v}_1, \dots, \vec{v}_n\}$ , then basis of  $V^\perp$  is  $\text{null}(A^T)$ , where  $A = \begin{bmatrix} | & & | \\ \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \\ | & & | \end{bmatrix}$

## ⑥ Orthogonal Linear Transformation

Def:  $T: V \rightarrow V$  is orthogonal if  $\langle T(\vec{v}), T(\vec{w}) \rangle = \langle \vec{v}, \vec{w} \rangle, \quad \forall \vec{v}, \vec{w} \in V$

Properties: ①  $\|T(\vec{v})\| = \|\vec{v}\|$  preserve length

② preserve angle

③  $\|T(\vec{v}) - T(\vec{w})\| = \|\vec{v} - \vec{w}\|$  preserve distance

④ the standard matrix of  $T$ 's columns are orthonormal and  $A^T A = I_n$

Projection matrix:  $\text{Proj}_{\vec{w}} \vec{v} = P\vec{v}$  where  $\{\vec{b}_1, \dots, \vec{b}_n\}$  is an orthogonal basis for  $W$  and  $A = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \dots & \vec{b}_n \end{bmatrix}$ ,  $P = A(A^T A)^{-1} A^T$

Property:  $P^2 = P$  (idempotent)

QR:  $A = QR$  where  $\text{col}(A)$  is LI,  $Q$  is orthonormal matrix,  $R$  is upper-triangular matrix

$P = P^T$  (symmetry)

$Q = \text{col}(A)$  has Gram-Schmidt and  $R = Q^T A$

Least square method

$$A\vec{q} = \text{Proj}_{\text{col}(A)} \vec{b} \Rightarrow A\vec{q} = A(A^T A)^{-1} A^T \vec{b} \Rightarrow \vec{y} = (A^T A)^{-1} A^T \vec{b} \rightarrow (A^T A)^{-1} A^T \vec{b} = ((QR)^T (QR))^{-1} (QR)^T \vec{b} = R^{-1} Q^T \vec{b}$$

## ⑦ Bilinear Transformation

$$\text{Def: } f(r\vec{v}_1 + \vec{v}_2, \vec{w}) = r f(\vec{v}_1, \vec{w}) + f(\vec{v}_2, \vec{w})$$

$$f(\vec{v}, r\vec{w}_1 + \vec{w}_2) = r f(\vec{v}, \vec{w}_1) + f(\vec{v}, \vec{w}_2)$$

Multilinear  $\approx$  Bilinear but multiple inputs instead of 2.

• alternating (when two inputs the same):  $f(\vec{v}_1, \dots, \vec{v}_i, \dots, \vec{v}_i, \dots, \vec{v}_n) = 0$

• skew-symmetric (switch two inputs' position):  $f(\vec{v}_1, \dots, \vec{v}_i, \dots, \vec{v}_j, \dots, \vec{v}_i, \dots, \vec{v}_n) = -f(\vec{v}_1, \dots, \vec{v}_j, \dots, \vec{v}_i, \dots, \vec{v}_n)$

alternating  $\Leftrightarrow$  skew-symmetric

determinant map from  $(\mathbb{R}^n)^n \rightarrow \mathbb{R}$  is  $D(e_1, \dots, e_n) = 1$

A  $n$ -box made with  $n$  linearly independent vectors in  $\mathbb{R}^n$  is measured with  $\gamma \in [0, \infty)$

$$\det(T(\vec{v})) = |\det(T)| |\det(\vec{v})|$$

↳ when  $A$  is not nxn,  $= \sqrt{|\det(A^T A)|}$  apply both for  $\det(T)$  and  $\det(\vec{v})$

$$\det(T) = \det([T]_B)$$
 where  $B$  is orthonormal basis for  $V$  if  $T: V \rightarrow V$

$A$  is diagonalizable  $\Leftrightarrow \exists$  diagonal  $D$ , invertible  $P$  s.t.  $A = PDP^{-1}$

$$T: V \rightarrow V$$

$T(\vec{v}) = \lambda \vec{v}$ ,  $\vec{v}$  is called the eigenvector of  $T$  and  $\lambda$  is the corresponding eigenvalue

$T: V \rightarrow V$  is diagonalizable if  $\exists$  a basis  $B$  for  $V$  s.t.  $[T]_B$  is diagonal

## (8) Complex System

$z = (a+bi), w = (c+di), zw = (ac-bd) + i(ad+bc)$

- Def of complex vector space  $V$ :
- ① nonempty
  - ②  $+: V \times V \rightarrow V$  and  $\cdot: \mathbb{C} \times V \rightarrow V$
- $\langle z, w \rangle_{\mathbb{C}} = \bar{z} \cdot w$       ③  $A_1 \sim A_2, S_1 \sim S_2$

Property of Euclidean Inner Product over  $\mathbb{C}$

- ①  $\langle z_1+w_1, z_2+w_2 \rangle_{\mathbb{C}} = \langle z_1, z_2 \rangle_{\mathbb{C}} + \langle w_1, w_2 \rangle_{\mathbb{C}}$     ②  $\langle r z, w \rangle_{\mathbb{C}} = \bar{r} \langle z, w \rangle_{\mathbb{C}}$     ③  $\langle z, r w \rangle_{\mathbb{C}} = r \langle z, w \rangle_{\mathbb{C}}$     ④  $\langle z, w \rangle_{\mathbb{C}} = \overline{\langle w, z \rangle_{\mathbb{C}}}$     ⑤  $\langle z, z \rangle_{\mathbb{C}} \geq 0$  and  $\langle z, z \rangle_{\mathbb{C}} = 0$  iff  $z=0$

Def of hermitian inner product is  $\langle \cdot, \cdot \rangle_{\mathbb{C}}: V \times V \rightarrow \mathbb{C}$  s.t satisfies ①-⑤ and  $\langle z, w \rangle_{\mathbb{C}} = \bar{z}^T w$

Property of \*

①  $(A+B)^* = A^* + B^*$

②  $(rA)^* = \bar{r} A^*$

③  $(AB)^* = B^* A^*$

R	C
$\langle \cdot, \cdot \rangle$	$\langle \cdot, \cdot \rangle_{\mathbb{C}}$
$V \cdot W = V^T W$	$\langle v, w \rangle = v^* w$
$A = A^T$ sym	$A = A^*$ Hermitian
$U^T U = U U^T = I_n$	$U U^* = U^* U = I_n$
orthogonal	unitary

Def  $A \in M_{n \times n}(\mathbb{C})$  is called Hermitian if  $A = A^*$

Def  $A \in M_{n \times n}(\mathbb{C})$  is called unitary if  $A^* A = A A^* = I_n$

columns of Unity matrix are orthonormal basis (just like orthogonal matrix, so  $U^* U = I_n$ )

Fundamental Thm of Algebra: Any polynomial of degree  $n$  over  $\mathbb{C}$  has  $n$  complex vectors

Def  $A \in M_{n \times n}(\mathbb{R})$  is called orthogonally diagonalizable if  $\exists$  diagonal  $D$  and orthogonal  $U$ , s.t  $A = U D U^T$

Def  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is orthogonally diagonalizable if  $\mathbb{R}^n$  has an orthonormal eigenbasis of  $T$

Def  $A \in M_{n \times n}(\mathbb{C})$  is called unitary diagonalizable if  $\exists$  a diagonal  $D$ , and a unitary  $U$  s.t  $A = U D U^*$

Def  $T: \mathbb{C}^n \rightarrow \mathbb{C}^n$  is called unitary diagonalizable if  $\mathbb{C}^n$  has an orthonormal eigenbasis of  $T$ .

Spectral Thm (for complex matrices)

$A \in M_n(\mathbb{C})$ . If  $A$  is Hermitian then  $A$  is U.D. And all eigenvalues of  $A$  are real numbers.  
(i.e.  $A=A^*$  then  $\exists$  unitary  $U$ ,  $\exists$  diagonal  $D$ ,  $D \in M_n(\mathbb{R})$  s.t.  $A=UDU^*$ )

Spectral Thm (for real matrices)

$A \in M_n(\mathbb{R})$ . If  $A$  is sym. then  $A$  is O.D

(i.e.  $A=A^T$  then  $\exists$  orthogonal  $U$  and  $\exists$  diagonal  $D$ ,  $U \in M_n(\mathbb{R})$  s.t.  $A=UDU^T$ )

Def  $A, B \in M_n(\mathbb{C})$ ,  $A$  is unitary equivalent to  $B$  if  $\exists$  unitary matrix  $U$  s.t.  $A=UBU^*$

$$A \underset{U.E}{\sim} B$$

Thm  $A$  is U.D  $\Leftrightarrow A$  U.E to a diagonal matrix

Def A matrix  $A \in M_n(\mathbb{C})$ , is called normal if  $AA^* = A^*A$

Thm  $A \in M_n(\mathbb{C})$ ,  $A$  is U.D  $\Leftrightarrow A$  is normal

Lemma: If  $A$  is normal and  $A \underset{U.E}{\sim} B$ , then  $B$  is normal

## ⑨ Jordan Block

Def A non matrix of the form  $\begin{bmatrix} \lambda & 1 & 0 \\ 0 & \ddots & \vdots \\ 0 & \vdots & \lambda \end{bmatrix}$  is called Jordan block

Def A matrix  $A = \begin{bmatrix} J_1 & 0 \\ 0 & J_n \end{bmatrix}$ , where  $J_i$  are Jordan block is called to be in Jordan Canonical form